

Let X be a top space. We wish to develop an 'invariant' of X :

Combinatorial description
of X



$\mathbb{Z}$ -graded $\mathbb{Z}$ -module

$\uparrow$ one $\mathbb{Z}$ -module per dimension
 $d \geq 0$, actually

$\nearrow$ i.e. well-defined
assignment to X

called the "homology of X ".

Next two weeks: Discuss multiple (equivalent) definitions of
"the homology":

① simplicial homology

- computed from a Δ -complex structure on X

② singular homology

- less straight forward / combinatorial but more robust

Sometimes properties are easier to prove when the
construction is more robust...

③ CW homology

- computed from a CW-complex structure on X
- most computationally efficient, most practical
and the one you really ought to learn to compute!

④* Čech cohomology

- "local-to-global" flavor, eg. sheaf theoretic
- we may only touch upon this briefly

First things first This week:

- how to construct/deconstruct Δ -complexes,
many examples to keep in your pocket
- translation to algebra, i.e. the simplicial chain cpx
- * Along the way, will introduce language of homotopy theorists
i.e. viewing these simplicial structures purely
"combinatorially" $\leftarrow$ discrete data, ordered sets, ...

later on (next week)

- properties, structure theorems, cut+paste computation methods...
- equivalences among the different constructions

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In these notes:

- "eg" = example
- "ex" = exercise
- = defining this term
- underline for emphasis.

* These are my lecture notes.
And the exercises are not
fleshed out here; just
reminders to set of ideas.

Simplicies plural of "simplex"

basic building blocks for (some) spaces

defn The n -simplex Δ^n is the convex hull of

the $n+1$ points $\{v_0, \dots, v_n\} = \{(1, 0, \dots, 0), \dots, (0, \dots, 0, 1)\}$

- conv. to the standard basis vectors $e_1, \dots, e_n$
- v_i for "vertices"

$$\Delta^n := \left\{ \underbrace{(t_0, \dots, t_n)} \in \mathbb{R}^{n+1} \mid \sum_i t_i = 1, t_i \geq 0 \forall i \right\}$$

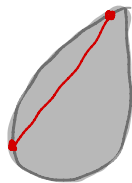
$= \sum_{i=0}^n t_i v_i$ since our v_i are standard!

Aside The convex hull of a set of points $P = \{p_1, \dots, p_k\}$ in $\mathbb{R}^N$ is the smallest convex set containing all points in P

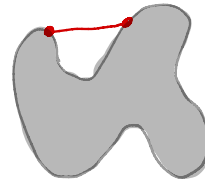
↖ For any $x, y \in S$, all points on the line b/w x and y , are also in S

Convex:

Some examples
in $\mathbb{R}^2$:



Not convex:



This is equivalent to the set of all linear combinations of points $p_i \in P$ where the nonnegative weights t_i add up to 100%:

$$\text{Hull}(P) = \left\{ \sum_{i=1}^k t_i p_i \mid \sum_{i=1}^k t_i = 1, t_i \geq 0 \forall i \right\}$$

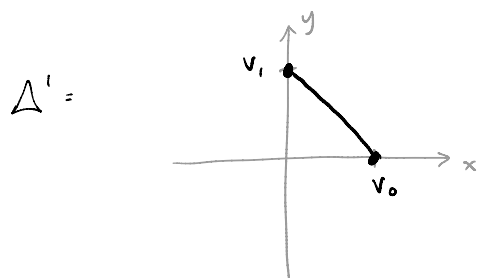
eg. the first few simplices:

(geometrically)

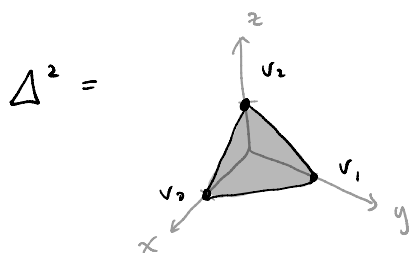


(abstractly / combinatorially)

the ordered set
 $[0] = \{0\}$. actually (0)
 b/c ordered.



the ordered set
 $[1] = \{0, 1\}$ is $(0, 1)$

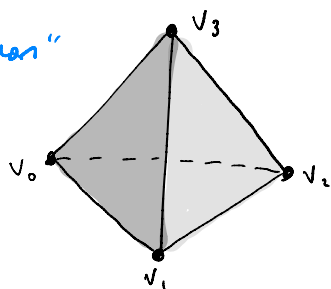


the ordered set
 $[2] = \{0, 1, 2\}$ is $(0, 1, 2)$

$\Delta^3 = \dots$ well it looks like this, but embedded in $\mathbb{R}^4$:

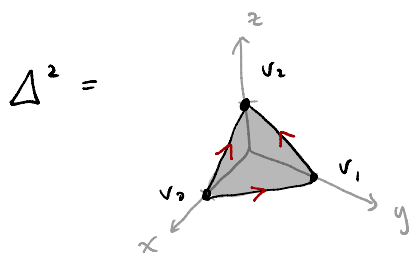
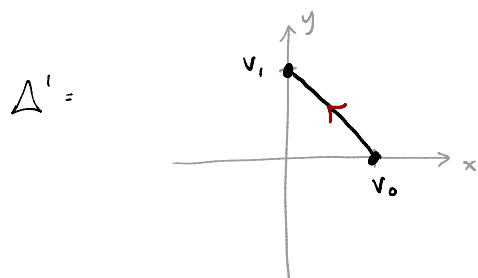
the ordered set $[3]$

"tetrahedron"

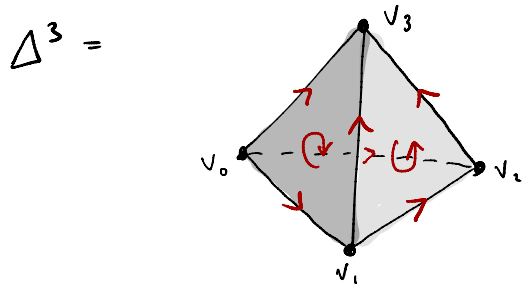


Remark. Δ^n is an n -dim manifold, ie for any point in the interior, a neighborhood looks like $\mathbb{R}^n$.

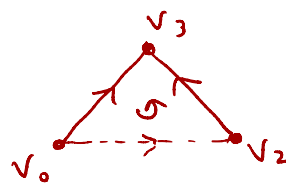
The ordering on the vertices determines an orientation on all the faces of a simplex:



interior orientation: $\curvearrowright$ ccw



back orientation:



bottom orientation:



These orientations are very important when we convert to algebra!

notation we capture all the abstract data of the n -simplex by the ordered set

$$[n] := \{0, 1, 2, \dots, n\}$$

maybe one likes to write $(0, 1, \dots, n)$ but I'm not thinking of these as coordinates...

with the total ordering $\leq$.

⚠ Some notation warnings:

- In CS, $[n]$ usually means $\{1, 2, \dots, n\}$
- In homological algebra, $[n]$ means degree shift of n
- In quantum algebra, $[n]$ is a quantum integer.

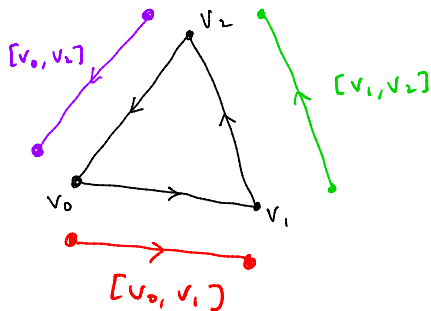
defn A face (really, "subsimplex") of a simplex Δ^n

is the subsimplex with vertices a nonempty subset of $\{v_0, \dots, v_n\}$.

- A k -dim face of Δ^n (where $0 \leq k \leq n$) is a subsimplex homomorphic to Δ^k
- Hatcher's notation: the subsimplex with vertices $v_{i_1}, v_{i_2}, \dots, v_{i_k}$ with $i_1 < i_2 < \dots < i_k$ is written $[v_{i_1}, v_{i_2}, \dots, v_{i_k}]$
- A k -dim face of Δ^n corresponds to an order-preserving map $[k] \longrightarrow [n]$.

eg. Δ^2 has 3 codimension-1 (ie dimension 1) faces:

If X is n dim'l,
and $S \subset X$ is d dim'l,
the codim of S is $n-d$.



These can be written using "delete" notation:

- $[v_1, v_2] = [\hat{v}_0, v_1, v_2]$
- $[v_0, v_2] = [v_0, \hat{v}_1, v_2]$
- $[v_0, v_1] = [v_0, v_1, \hat{v}_2]$

These also correspond to the 3 order-preserving maps

$[1] \rightarrow [2]$:

- $[v_1, v_2] = [\hat{v}_0, v_1, v_2] : 0 \mapsto 1, 1 \mapsto 2$
- $[v_0, v_2] = [v_0, \hat{v}_1, v_2] : 0 \mapsto 0, 1 \mapsto 2$
- $[v_0, v_1] = [v_0, v_1, \hat{v}_2] : 0 \mapsto 0, 1 \mapsto 1$

ex. "ex" = exercise in my notes; "eg" = example

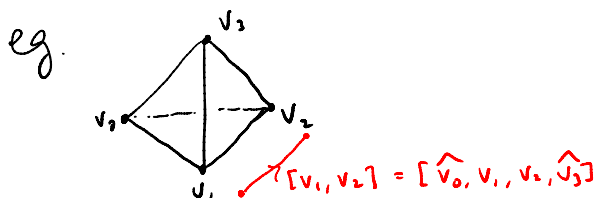
(a) How many faces of dimension k are there in Δ^n ?

$\binom{n+1}{k+1}$ faces. You keep $k+1$ vertices.

(b) How many faces does Δ^n have total?

nonempty subsets of $[n] = 2^{n+1} - 1$.

ex. Identify and draw all faces of Δ^3 , w/ orientation for dim 1 and 2 faces.



Δ -complexes

(soft intro)

Informal defn

A Δ -complex is a quotient space of a collection of disjoint simplices obtained by identifying faces in the order-preserving way

eg $S^1 = \text{the circle}$

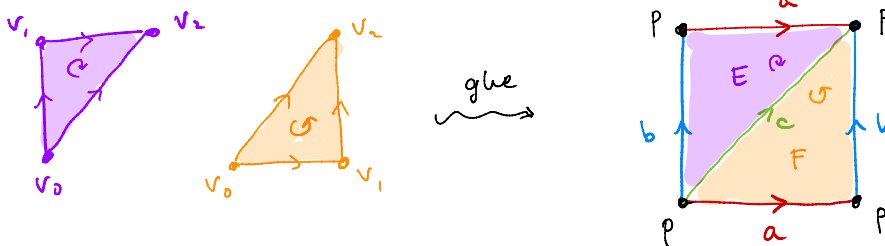


There are many different ways to build S^1 !

eg. $S^2 = \text{the sphere}$



eg. the torus $T = S^1 \times S^1$:



Here is the formal definition:

defn. Let X be a topological space.

A Δ -complex structure on X is a collection of maps

$$\{\sigma_\alpha: \Delta^{n(\alpha)} \rightarrow X\}_{\alpha \in A} \quad \text{such that}$$

$$\boxed{\Delta-1} \quad \forall \alpha \in A, \quad \sigma_\alpha|_{\text{int}(\Delta^{n(\alpha)})} \text{ is injective}$$

and each point in X is in the image of exactly one such restriction

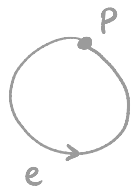
* Caveat For $S \subset \mathbb{R}^d$, the interior $\text{int}(S)$ of S is defined to be the union of all open subsets U of $\mathbb{R}^d$ contained in S :

$$\text{int}(S) = \bigcup \{U \subset \mathbb{R}^n \mid U \subseteq S\}.$$

Since Δ^0 is a single point in $\mathbb{R}^1$, $\text{int}(\Delta^0) = \emptyset \dots$

So, for the purposes of this definition, say " $\text{int}(\Delta^0) = \Delta^0$ ".

eg. $X = S^1$



point p is in the image of

$$\sigma_p: \Delta^0 \rightarrow X$$

but not in $\sigma_e|_{\text{int}(\Delta^1)}: \text{int}(\Delta^1) \rightarrow X$.

$\boxed{\Delta-2}$ Each restriction $\sigma_\alpha|_{\text{face } F \text{ of } \Delta^{n(\alpha)}}$ where $F \cong \Delta^k$

is equal to some map $\sigma_\beta: \Delta^k \rightarrow X$



Here we need to identify $\Delta^{n(\beta)} = \Delta^k$, the src of σ_β with the face F of $\Delta^{n(\alpha)}$ in the order preserving way.

⚠ There are geometric concerns about parametrization.

We claim there is an "obvious" canonical way to identify F with Δ^k in the order-preserving way and speak no more of this.

$\boxed{\Delta-3}$ $U \subset X$ is open $\iff \forall \alpha \in A, \sigma_\alpha^{-1}(U)$ is open.

//

Rmk. (Casual interpretation of the requirements)

($\Delta-1$) tells us that X is built specifically and entirely from these pieces.

($\Delta-2$) tells us that if a simplex Δ^n is used to build X , then all its faces (subsimplices) are also part of the construction, i.e. they are domains of other maps in the collection.

($\Delta-3$) tells us that the quotient topology on the constructed space agrees with the topology of the originally given space X .

mk. (Aside)

- ① Cardinality of A need not be finite, but we will mostly work with finite data

ex. (Remark about cardinality of A). Put a Δ -complex structure on the Hedgehog space for cardinality K .

- ② Not all spaces have a Δ -structure!

Fact A closed 4-mfld is triangulable iff it is smoothable.

I have not provided a definition here, but it is equivalent to being the geom. realization of a simplicial set.

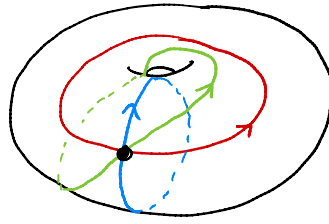
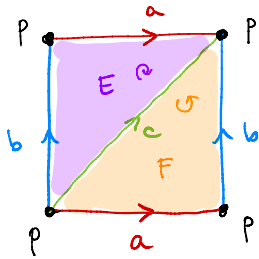
eg. The E^8 manifold (!! It's even a manifold!) is not triangulable.

- ③ However, Fact every manifold is homotopic (but not necessarily homeomorphic) to a CW complex. 😊

↪ we'll get there.

Examples *Keep these in your pocket!*

eg. Thus $T = S' \star S'$ (more formally how)



The collection of maps: $|A| = 6$ maps

- $\sigma_p: \Delta^0 \rightarrow X$ sends $v_0 \mapsto p$
 - $\sigma_a: \Delta^1 \rightarrow X$ sends $[v_0, v_1]$ to a
 - $\sigma_b: \Delta^1 \rightarrow X$ sends $[v_0, v_1]$ to b
 - $\sigma_c: \Delta^1 \rightarrow X$ sends $[v_0, v_1]$ to c
- } via the "canonical" (i.e. obvious) homeomorphism

All three of $\sigma_a, \sigma_b, \sigma_c$ send the endpoints $v_0, v_1 \mapsto p$

- $\sigma_E: \Delta^2 \rightarrow X$ sends $[v_0, v_1, v_2] \rightarrow E$

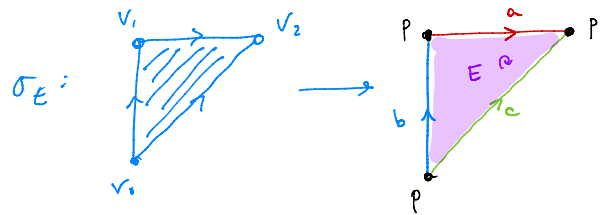
and in particular sends

$$[v_0, v_1] \rightarrow b$$

$$[v_1, v_2] \rightarrow a$$

$$[v_0, v_2] \rightarrow c$$

and sends $[v_0], [v_1], [v_2] \rightarrow p$.



- $\sigma_F: \Delta^2 \rightarrow X$ sends $[v_0, v_1, v_2] \rightarrow F$

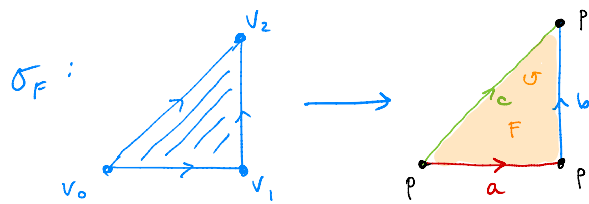
and in particular sends

$$[v_0, v_1] \rightarrow a$$

$$[v_1, v_2] \rightarrow b$$

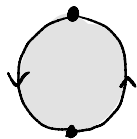
$$[v_0, v_2] \rightarrow c$$

and sends $[v_0], [v_1], [v_2] \rightarrow p$.



eg. $\mathbb{RP}^2$: 2-dim real projective space
 $= S^2 / \sim$ where $\sim$ identifies antipodal points

We often think of $\mathbb{RP}^2$ topologically as the space we get from identifying two sides of a bigon:

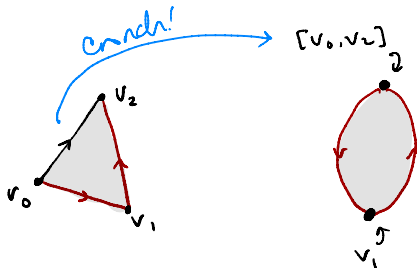


Δ NOT a duple.
 Note the orientations.

This is not a Δ -complex structure. Here's a thought process:

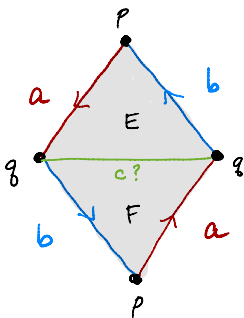
Attempt 1: Bad

Let's try a single Δ^2 :



Violates
 $\Delta-1$
 injectivity.

Attempt 2: better, but still not legal



Now the path ba is mapped to the "seam"

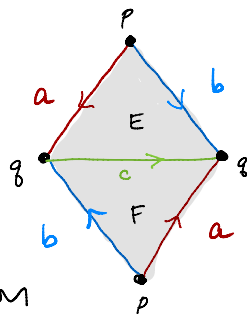
There is no way to orient c so that

$$\sigma_E|_{\text{face "c"}} = \sigma_F|_{\text{face "c"}}$$

Either choice violates $\Delta-2$.

Attempt 3 slight modification, how good

Just reverse the orientation of b :



Verify that now:

$$\sigma_E|_{[v_1, v_2]} = \sigma_c = \sigma_F|_{[v_0, v_1]}$$

We choose an orientation on c .

(Δ -)

ex. Build simplicial structures for

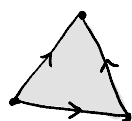
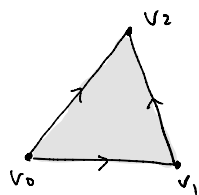
(a) spheres of all dims

(b) cco surfaces cco = closed, catd, orientable

(c) cc, non-orientable surfaces

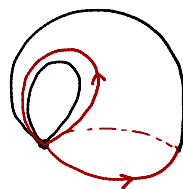
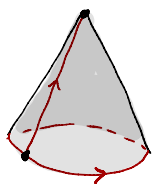
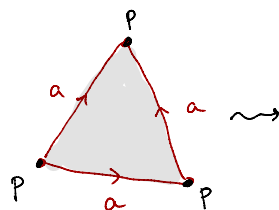
(d) n-torus

eg. "Dunce cap" what can I make with just one Δ^2 (+ all faces)?



i.e. identify all 3 sides, according to these orientations!

One can literally crochet/knit/darn this! (in $\mathbb{R}^3$!)



then identify the red circles...

ex. (maybe) Challenge / review for 215a:

Show that the dunce cap is $\cong D^2 \subseteq *$ (homotopy equiv to a point!).

Soft intro to simplicial homology chain complex

We wish to translate the Δ -cpx structure to algebra, in the form of a chain complex of abelian groups.

↳ later we'll see that the homology of this chain cpx does not depend on the choice of Δ -cpx structure.
But for now we just want to build a chain cpx.

Chain complex: 2 pieces of data:

- a $\mathbb{Z}$ -mod C_i for each dimension $i \in \mathbb{Z}$ "chain groups"
(most are 0, and for us $C_i = 0$ when $i < 0$).
- a "differential", ie maps $\partial_i: C_i \rightarrow C_{i-1} \quad \forall i$.
Such that $\partial^2 = 0$ ie $\partial_{i+1} \circ \partial_i = 0 \quad \forall i$.

In our case, $C_i = \mathbb{Z} \langle \{\sigma_\alpha\} \mid n(\alpha) = i \rangle$

and ∂_i records the image of $\partial \Delta^{n(\alpha)}$.

↳ also sometimes called "the boundary map" for this reason.

eg. $\Delta' = v_0 \rightarrow v_1$ is a space with a Δ cpx structure, where the σ_α are inclusions.

0-simplices: $\sigma_\alpha: \Delta^0 \rightarrow \Delta'$ $\sigma_\beta: \Delta^0 \rightarrow \Delta'$
 $v_0 \mapsto v_0$ $v_0 \mapsto v_1$

1-simplicies: $\sigma_\gamma: \Delta' \rightarrow \Delta' = \text{id}_{\Delta'}$

} Blue Δ' is thought of as the top space, ie $X = \Delta'$.

Chain complex let $X = \Delta'$

Here's what's actually happening:

chain groups: $C = \bigoplus_{i \in \mathbb{Z}} C_i$, $C_0 = \mathbb{Z}\langle \sigma_\alpha, \sigma_\beta \rangle$, $C_1 = \mathbb{Z}\langle \sigma_\gamma \rangle$,
 all other $C_i = 0$.

differential: $\partial_i: C_i \rightarrow C_0$ is determined by
 $\sigma_\gamma \mapsto \sigma_\beta - \sigma_\alpha$
 (all other $\partial_i = 0$)

How did I get this? We actually think about where the boundaries of $\Delta^{n(\alpha)}$ are sent!

We actually may identify σ_α with its image in this example

so we may write (as we did Wednesday):

$\partial[v_0, v_1] = [v_1] - [v_0]$
 ↑ Final initial.

I omitted the subscript bc I can think of

$\partial = \bigoplus_i \partial_i$ as a total differential on the
 module $C = \bigoplus C_i$

Since all other $\partial_i = 0$, it is clear that ∂ satisfies $\partial^2 = 0$.

↳ ex. If you've never seen this before, write $\partial = \partial_0 + \partial_1 + \dots$
 and write down the graded pieces of the equation
 to deduce that $\partial_{i+1} \circ \partial_i = 0$.

Quick start guide to chain complexes, homology

Let's start with some algebra. Then we'll describe simplicial homology formally with additional standard notation, terminology

- **Chain groups**: $C = \bigoplus C_i$
- **differential**: $\partial = \sum \partial_i$, where $\partial^2 = 0$
- **chain complex**: (C, ∂)
- **homology functor**: $\{\text{chain cpxs}\} \longrightarrow \{\text{graded } \mathbb{Z}\text{-mods}\}$

$$\text{by } H_i = \frac{\ker \partial_i}{\text{im } \partial_{i+1}}$$

↑ cycles
↑ boundaries

note This is only ok to write if you know $\text{im } \partial_{i+1} \subset \ker \partial_i$.
This is ensured by $\partial_{i+1} \circ \partial_i = 0$.

- Two cycles are **homologous** if they differ by a boundary. Then they represent the same **homology class**.
- The point of homology: associating different decompositions of the space X (diff Δ -structures) may yield different chain complexes, but these all compute the same homology groups $\{H_i(X)\}_{i \in \mathbb{Z}}$. (all together, we write $H_*(X)$).

* This point is very top-spaces-centric. In general:

$$\underbrace{\text{chain htpy equivalence}} \Rightarrow \underbrace{\text{quasi-isomorphism}}$$

stronger equivalence; analogous to "homotopy equiv" for topspaces

= have the same homology groups

- "**graded**" just means you associate integers (the dimension) to different pieces of (C, ∂)

Simplicial Homology

- let X be a Δ -complex.
- let $\Delta_n(X)$ be the free abelian group generated by the open n -simplices e_α^n of X .



- By $\Delta-1$, it's ok to think of these e_α^n as part of X , the target of the map $\sigma_\alpha: \Delta^n \rightarrow X$

We call σ_α the characteristic map of e_α^n .

- We write each element as finite formal sums

$$\sum_{\{\alpha \in A \mid n(\alpha) = n\}} c_\alpha \cdot \sigma_\alpha$$

↑ b/c we are working with $\mathbb{Z}\sigma_\alpha \oplus \mathbb{Z}\sigma_\beta \oplus \dots \leftarrow$ direct sums.

or we could write $\sum c_\alpha e_\alpha^n$, but I won't, in general...

- The boundary homomorphism $\partial_n: \Delta_n(X) \rightarrow \Delta_{n-1}(X)$ is given by

$$\partial_n(\sigma_\alpha) = \sum_i (-1)^i \sigma_\alpha \big|_{[v_0, \dots, \widehat{v_i}, \dots, v_n]}$$

↑ basis elt.
↑ where $n(\alpha) = n$

by $\Delta-2$ we have this map as a basis element for $\Delta_{n-1}(X)$

Claim (lemma 2.1) let $\mathcal{C} = \bigoplus_n \Delta_n(X)$ and $\partial = \sum_n \partial_n$

Then $(\mathcal{C}, \partial)$ is a chain complex.

Pf.

It suffices to show that the composition

$$\Delta_n(X) \xrightarrow{\partial_n} \Delta_{n-1}(X) \xrightarrow{\partial_{n-1}} \Delta_{n-2}(X)$$

is the zero map.

Calculate directly from the definition:

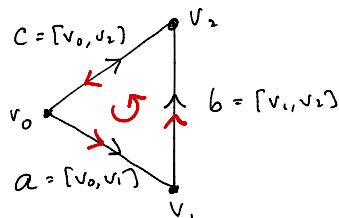
$$\partial_n(\sigma) = \sum_i (-1)^i \sigma|_{[v_0, \dots, \hat{v}_i, \dots, v_n]}$$

$$\partial_{n-1} \partial_n(\sigma) = \sum_{j < i} (-1)^i (-1)^j \sigma|_{[v_0, \dots, \hat{v}_j, \dots, \hat{v}_i, \dots, v_n]} + \sum_{j > i} (-1)^i (-1)^{j-1} \sigma|_{[v_0, \dots, \hat{v}_i, \dots, \hat{v}_j, \dots, v_n]}$$

note the
parity change
b/c v_i was
deleted!

opp signs.
These
cancel.

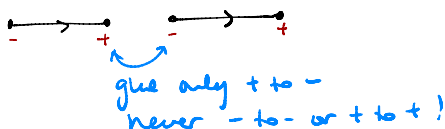
Remark What's happening topologically?



on a simplex, with orientations of codim 1

faces determined by the ∂ orientation of the interior (ie "cyclic", at least in the shown dimension),

all codim 2 faces are used twice, but w/ opp. sign (orientation)



Defn We call $H_*(\mathcal{C}, \partial)$ the simplicial homology of X

and write it as $H^*(X) = \bigoplus_n H_n(X)$