

# MAT 150A HW01

[ADD YOUR NAME HERE]

Due Tuesday, 10/10/23 at 11:59 pm on Gradescope

**Reminder.** Your homework submission must be typed up in full sentences, with proper mathematical formatting. The following resources may be useful as you learn to use TeX and Overleaf:

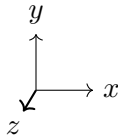
- Overleaf's introduction to LaTeX:  
[https://www.overleaf.com/learn/latex/Learn\\_LaTeX\\_in\\_30\\_minutes](https://www.overleaf.com/learn/latex/Learn_LaTeX_in_30_minutes)
- Detexify:  
<https://detexify.kirelabs.org/classify.html>

**Covered in this HW** Parts of Chp. 1, esp. §1.5, 2.1–2.4. Matrices, rotations, definition of a group, symmetric groups and permutations, etc.

**Grading** Some of the (parts of) problems will be graded in detail out of several points, and necessary feedback will be given. The rest will be graded out of 2 points. I will reveal which problems are fully graded in the solutions, which will be posted on the Friday following the due date.

## Exercise 1

In Lecture 1, we described a group  $G$  generated by rotations of  $\theta = \frac{\pi}{4}$  about the  $x$ -,  $y$ -, and  $z$ - axes. To be more precise, we set a convention for the coordinate axes



( $e_3$  points out of the board)

and wrote down the associated matrices for our chosen generators:

$$p = \begin{pmatrix} 1 & 0 & 0 \\ 0 & \cos \theta & \sin \theta \\ 0 & -\sin \theta & \cos \theta \end{pmatrix} \quad y = \begin{pmatrix} \cos \theta & 0 & -\sin \theta \\ 0 & 1 & 0 \\ \sin \theta & 0 & \cos \theta \end{pmatrix} \quad r = \begin{pmatrix} \cos \theta & -\sin \theta & 0 \\ \sin \theta & \cos \theta & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

Since  $\theta = \frac{\pi}{4}$ ,  $\cos \theta = \sin \theta = \frac{1}{\sqrt{2}} := t$ , so we can rewrite our matrices as follows:

$$p = \begin{pmatrix} 1 & 0 & 0 \\ 0 & t & t \\ 0 & -t & t \end{pmatrix} \quad y = \begin{pmatrix} t & 0 & -t \\ 0 & 1 & 0 \\ t & 0 & t \end{pmatrix} \quad r = \begin{pmatrix} t & -t & 0 \\ t & t & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

We used spatial reasoning to try to find a sequence (composition) of the actions (elements of  $G$ )  $p, p^{-1}, y, y^{-1}$  that is equal to  $r$ ; this would prove that only  $G$  is generated by  $\{p, y\}$ , and in particular,  $r$  is not needed as a generator. Some guesses included  $p^2y^{-1}p^{-2}$  and  $py^{-1}p^{-1}$ .

*Typesetting tip: To typeset matrices, copy and paste my code for typesetting matrices above, then modify the entries.*

- (a) Find matrices representing  $p^{-1}$  and  $y^{-1}$ ; prove that these are indeed inverses to  $p$  and  $y$ , respectively.
- (b) Use matrix multiplication and trigonometric identities to compute  $p^2y^{-1}p^{-2}$  and  $py^{-1}p^{-1}$ . Which of these, if any, is equal to  $r$ ?

SOLUTION.

## Exercise 2

In this exercise, you will explore the symmetric group on 4 indices,  $S_4$ . First, read page 42 of the text to see how  $S_3$  is described. Lecture 2 and the accompanying note may also be useful.

**Warning** The text defines a *transposition* to be any 2-cycle  $(i\ j)$ . In class, we restricted this definition to 2-cycles involving only adjacent indices, i.e.  $\tau_i = (i\ i+1)$ .

- (a) Write the permutations

$$p = (1\ 2\ 3\ 4) \quad q = (1\ 3\ 2\ 4) \quad r = (1\ 4\ 2)$$

as products of (adjacent) transpositions  $\tau_i$ .

- (b) In class, we discussed why the set of transpositions  $\{\tau_1, \tau_2, \tau_3\}$  generate  $S_4$  *intuitively*, but we did not prove it:

**Proposition (A).** The symmetric group  $S_n$  is generated by the set of (adjacent) transpositions  $\{\tau_1, \tau_2, \dots, \tau_{n-1}\}$ .

Assuming Proposition A is true, prove that  $S_4$  is generated by  $\{(1\ 2), (1\ 2\ 3\ 4)\}$ .

*Hint: Can you show that  $\tau_2$  and  $\tau_3$  are generated by these two elements?*

SOLUTION.

## Exercise 3

This exercise focuses on permutation matrices and determinants. For a refresher on determinants, see §1.4 in the text. In particular, we will need the following facts, labeled here as Lemmas A and B:

**Lemma (A).** The determinant of the  $n \times n$  identity matrix  $I_n \in M_{n \times n}(\mathbb{R})$  is 1.

**Lemma (B).** If  $M'$  is obtained from  $M$  by interchanging two different rows, then  $\det A' = -\det A$ .

We will also need the following definition:

**Definition** (Sign of a permutation). Let  $p \in S_n$  be a permutation. The **sign** of  $p$  is equal to the determinant of the permutation matrix  $P$  representing  $p$ :

$$\operatorname{sgn}(p) := \det(P).$$

(a) Prove that the transpose of a permutation matrix is its inverse.

(b) Prove that the determinant of a permutation matrix is always  $\pm 1$ .

*Therefore the sign of a permutation is always either  $+1$  or  $-1$ . If  $\operatorname{sgn}(p) = +1$ , we say that  $p$  is **even**; otherwise, if  $\operatorname{sgn}(p) = -1$ , we say that  $p$  is **odd**.*

(c) Let  $p \in S_n$ , and write  $p$  as a composition (or equivalently, product) of  $k$  transpositions:

$$p = \tau_{i_1} \circ \tau_{i_2} \circ \dots \circ \tau_{i_k}$$

Prove that  $p$  is even if and only if  $k$  is even, and that  $p$  is odd if and only if  $k$  is odd.

*In other words, we could define  $\operatorname{sgn}(p)$  to be  $(-1)^k$ , where  $k$  is the number of transpositions in any composition of transpositions equal to  $p$ .*

**SOLUTION.**