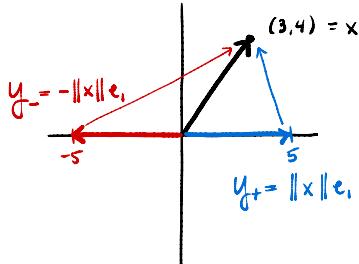


# LECTURE 18

Q. Write down the Householder reflection matrix that takes the vector  $x = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$  to a vector  $y$  in the direction of  $e_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

Find  $y$ . \*Choose a vector  $y$ !\*

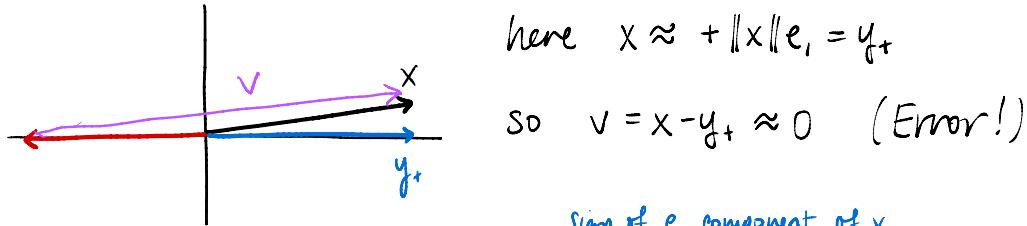
$\|x\| = \sqrt{3^2 + 4^2} = 5$ . There are two vectors:  $y = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$  or  $\begin{bmatrix} -5 \\ 0 \end{bmatrix}$



Recall: we want  $v = x - y$ ,  $u = \frac{v}{\|v\|}$ .

Then  $H = I - 2uu^T$ .

In general, we want to vector that is "most different" from  $x$ , because of situations like:



Best to always choose  $v = x + \underbrace{\text{sgn}(x_1)}_{\text{sign of } e_1 \text{ component of } x} \|x\| e_1$ :

$$v = x - y_- = x - (-\|x\|e_1) = \begin{bmatrix} 3 \\ 4 \end{bmatrix} + \begin{bmatrix} 5 \\ 0 \end{bmatrix} = \begin{bmatrix} 8 \\ 4 \end{bmatrix} = 4 \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

$$\|v\| = 4\sqrt{4+1} = 4\sqrt{5}$$

$$u = \frac{v}{\|v\|} = \frac{1}{4\sqrt{5}} \cdot 4 \begin{bmatrix} 2 \\ 1 \end{bmatrix} = \begin{bmatrix} \frac{2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix}$$

$$H = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - 2 \begin{bmatrix} \frac{2}{\sqrt{5}} \\ \frac{1}{\sqrt{5}} \end{bmatrix} \begin{bmatrix} \frac{2}{\sqrt{5}} & \frac{1}{\sqrt{5}} \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} - \begin{bmatrix} \frac{8}{5} & \frac{4}{5} \\ \frac{4}{5} & \frac{2}{5} \end{bmatrix} = \begin{bmatrix} -\frac{3}{5} & -\frac{4}{5} \\ -\frac{4}{5} & \frac{3}{5} \end{bmatrix}$$

\*

$H$  is an orthogonal matrix.  $y = Hx$

## MGS as triangular orthogonalization:

Let's write the algorithm as matrix operations:

Step  $i=1$

$$\underbrace{[v_1^{(1)} \ v_2^{(1)} \ \cdots \ v_n^{(1)}]}_{=A} \left[ \begin{array}{c|ccc} \frac{1}{r_{11}} & -\frac{r_{12}}{r_{11}} & \cdots & -\frac{r_{1n}}{r_{11}} \\ \hline 0 & I_{n-1} \end{array} \right] = \underbrace{[q_1 \ v_2^{(2)} \ \cdots \ v_n^{(2)}]}_{=AR_1}$$

triangular operation  
"R<sub>1</sub>"

Step  $i=2$

$$\underbrace{[q_1 \ v_2^{(2)} \ \cdots \ v_n^{(2)}]}_{AR_1} \left[ \begin{array}{c|ccc} 1 & 0 & \cdots & 0 \\ \hline 0 & \frac{1}{r_{22}} & -\frac{r_{23}}{r_{22}} & \cdots & -\frac{r_{2n}}{r_{22}} \\ 0 & 0 & I_{n-2} \end{array} \right] = \underbrace{[q_1 \ q_2 \ v_3^{(3)} \ \cdots \ v_n^{(3)}]}_{AR_2 R_3}$$

R<sub>2</sub>

$$\dots AR_1 R_2 \cdots R_n = \widehat{Q} = [q_1 \ \cdots \ q_n]$$

$$R_n = \begin{bmatrix} 1 & & 0 \\ & \ddots & \\ 0 & & 1 \end{bmatrix} \quad * \text{ Note that each } R_i \text{ is invertible!} \\ (\text{full rank, square matrix})$$

Let  $\widehat{R} = (R_1 R_2 \cdots R_n)^{-1}$ . Then  $A = \widehat{Q} \widehat{R}$  indeed.

\*

Householder Triangularization is orthogonal triangularization:

$$\begin{array}{c} \begin{bmatrix} \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \\ \cdot & \cdot & \cdot \end{bmatrix} \xrightarrow{Q_1} \begin{bmatrix} \Delta & \Delta & \Delta \\ 0 & \Delta & \Delta \\ 0 & \Delta & \Delta \\ 0 & \Delta & \Delta \end{bmatrix} \xrightarrow{Q_2} \begin{bmatrix} \Delta & \Delta & \Delta \\ 0 & \square & \square \\ 0 & 0 & \square \\ 0 & 0 & \square \end{bmatrix} \xrightarrow{Q_3} \begin{bmatrix} \Delta & \Delta & \Delta \\ 0 & \square & \square \\ 0 & 0 & \star \\ 0 & 0 & 0 \end{bmatrix} = R \\ A \qquad Q_1 Q_2 Q_3 A \qquad Q_3 Q_2 Q_1 A = R \end{array} \quad (\text{full } R!)$$

Let  $Q^T = Q_3 Q_2 Q_1$ . Then  $Q^T A = R \Rightarrow A = QR$  (full QR decomp)

Algorithm (Householder QR decomposition)  $A \in \mathbb{R}^{m \times n}$

for  $k = 1 : n$

$$x = A(k:m, k)$$

eg.  $n=3, m=4, k=2$ :

$$v_k = \text{sgn}(x_1) \|x\| e_1 + x$$

in standard basis for  $\mathbb{R}^{m-k+1}$   
 $= R_k \times R_{k+1} \times \dots \times R_m$

$$\begin{bmatrix} \Delta & \Delta & \Delta \\ 0 & \Delta & \Delta \\ 0 & \Delta & \Delta \\ 0 & \Delta & \Delta \end{bmatrix}$$

$$v_k = \frac{v_k}{\|v_k\|} \quad \text{normalized ("u_k")}$$

$$A(k:m, k:n) = \underbrace{A(k:m, k:n) - 2v_k v_k^T A(k:m, k:n)}_{(I - 2u_k u_k^T)(A(k:m, k:n))}$$

Output  $R$ , whose top square  $R$  is upper triangular

#

You might not wish to store the  $Q_i$  if not needed:

eg.  $Ax=b$  (determined or overdetermined)

If you have  $Q^T A = R$  as linear transformation,

then  $Rx = Q^T Ax$  ( $= Q^T b$  if  $Ax=b$  is determined)

so if we want  $\min_x \|b - Ax\|^2 = \min_x \|Q^T b - Q^T Ax\|^2$

$$= \min_x \|Rx - Q^T b\|$$

so we didn't need to store  $Q^T$ .

Note You could compute  $Q^T b$  by running the algorithm

for  $k=1:n$  on  $[a_1 \ a_2 \ \dots \ a_n \ | \ b]$

(not  $n+1$ !)

& not store  $Q^T$ .

### Numerical stability example

$$A = \begin{bmatrix} 1 & 1 & 1 \\ \varepsilon & \varepsilon & \varepsilon \end{bmatrix}$$

$$a_1 = [1 \ \varepsilon \ 0 \ 0]^T$$

$$a_2 = [1 \ 0 \ \varepsilon \ 0]^T$$

$$a_3 = [1 \ 0 \ 0 \ \varepsilon]^T$$

Using Householder reflections, we get

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ -\frac{1}{\sqrt{3}} & \frac{\sqrt{2}}{\sqrt{3}} & \frac{\sqrt{2}}{\sqrt{3}} \\ \frac{\sqrt{2}}{\sqrt{3}} & \frac{1}{\sqrt{3}} & \frac{1}{\sqrt{3}} \end{bmatrix} \underbrace{\begin{bmatrix} 1 & 1 & 1 \\ -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 1 \end{bmatrix}}_{Q^T} \underbrace{\begin{bmatrix} -1 & -\varepsilon & 1 \\ -\varepsilon & 1 & 1 \\ 1 & 1 & 1 \end{bmatrix}}_{Q_1} = \begin{bmatrix} -1 & -1 & -1 \\ \frac{2\varepsilon}{\sqrt{2}} & \frac{\varepsilon}{\sqrt{2}} & (\frac{1}{\sqrt{3}} + \frac{\sqrt{2}}{\sqrt{3}})\varepsilon \\ (\frac{1}{\sqrt{3}} + \frac{\sqrt{2}}{\sqrt{3}})\varepsilon & 1 & 1 \end{bmatrix} \underbrace{A}_{R}$$

$\Rightarrow A = QR$

$$\text{So } Q^T = Q_3 Q_2 Q_1 \quad \text{and } Q = (Q^T)^T = Q_1^T Q_2^T Q_3^T$$

$$\text{and } Q^T Q = Q_3 Q_2 \underbrace{Q_1}_\text{there are some epsilons here:} Q_1^T Q_2^T Q_3^T$$

$$Q_1^T Q_1 = \begin{bmatrix} -1 & -\varepsilon \\ -\varepsilon & 1 \end{bmatrix} \begin{bmatrix} -1 & -\varepsilon \\ -\varepsilon & 1 \end{bmatrix} = \begin{bmatrix} 1+\varepsilon^2 & 0 \\ 0 & 1+\varepsilon^2 \end{bmatrix} \approx I_2 !$$

Turns out  $Q^T Q \approx I_4$ ; only multiples of  $\varepsilon^2$  appear!